Performance of Parallel Concatenated Convolutional Codes (PCCC) with BPSK in Nakagami Multipath M-Fading Channel

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Abstract — In this paper the encoder design of two parallel concatenated convolutional codes (PCCC) have been introduced. Concept of puncturing is also considered. PCCC is also named as Turbo codes. Decoding process of turbo-codes using a maximum a posteriori (MAP) algorithm has been discussed. Different parameters affect the BER performance of turbo codes are introduced. The previous studies focusing on the turbo-codes performance in (AWGN) and Rayleigh multipath- fading channels [1], [2]. The real importance of Nakagami –m fading model lies in the fact that it can often be used to fit the indoor channel measurements for digital cellular systems such as global system mobile (GSM) [3]. In this paper, the BER performance and comparative study of turbo-codes in Nakagami multipath- fading channel is verified using Matlab simulation program.

Keywords — Turbo codes, Interleaver, Feedback Decoder.

I. INTRODUCTION

The invention of turbo- codes has been an unprecedented event in the field of communication. Turbo codes have been considered as a powerful error correcting codes for its superior performance so; it takes place in mobile communications area, high data rate internet applications and also in the field of steganography [4]. The design of these codes was a result of an experimental process where simulation was used in order to joint several parameters so as to optimize the final target, namely the bit error rate (BER) [5]. This paper is structured as follows; section-II introduces the puncture turbo encoder using a random interleaver. We concerned in section-III in Nakagami multipath- fading channel model. In section-IV decoding of turbo codes using feedback structure with Maximum Aposteriori Probability (MAP) algorithm has been investigated. Effect of input data frame length, encoder constraint length and the number of decoding iterations in the BER performance have been performed. Section-V performs the comparative study of BER performance in both Rayleigh and Nakagami multipath fading channels for code rates half and one-third and different Nakagami (m) shaping factor.

II. PUNCTURED TURBO ENCODER

Turbo-codes have an excellent coding community for their astonishing performance. They are parallel-concatenated convolutional codes (PCCC’s) whose encoder is formed by two or more constituent systematic recursive convolutional encoders joined by an interleaver [6]. The input information bits feed the first encoder, after have been scrambled by the interleaver, and enter the second encoder. The code word of the parallel-concatenated code consists of the information bits followed be the parity check bits of both encoders as shown in Fig.1 depending on the code rate required, the parity bits from the two constituent encoders are punctured before transmission. For example, constituent codes of rate 1/2 and for a turbo code of rate 1/3, all the parity bits are transmitted, whereas, for a turbo- code with rate 1/2, the parity bits from the constituent codes are punctured alternately. For transmission over a fading channel, the coded bits should be further interleaved by a channel interleaver before transmission [7]. The goal in designing turbo-codes is to choose the best encoder generator polynomials and a proper interleaver design to maximize the free distance of the code.

![Fig.1 General Diagram of Turbo Code Encoder](image-url)
\[ \text{Ir} = (\frac{M}{2} + 1) (i + j) \mod M \]  
(1)

\[ \xi = (i + j) \mod 8 \]  
(2)

\[ \text{jr} = \lfloor P(\xi)(J + 1) \rfloor - 1 \mod M \]  
(3)

Where \((i, r, j, r)\) are the addresses of line and column for reading. This nonuniform reading procedure is able to spread the residual error blocks, giving a large free distance to the concatenated (parallel) code [1].

### III. Nakagami Multipath Fading Channel

Nakagami -m distribution is a general probability density function (PDF). In creating a Nakagami -m distribution, Nakagami was able to span with one distribution the entire range from one-sided Gaussian fading (including Rayleigh fading) to a non-fading according to the scale and shape parameters \(\Omega, m\) [8]. Nakagami -m distribution is also of great interest to ionospheric physicists because amplitude fading due to ionospheric scintillation has been found following an m-distribution [9]. The (PDF) of Nakagami-m can be described as follows:

\[ P(r) = \frac{2m^m r^{2m-1}}{\Gamma(m)\Omega^m} e^{-\left(\frac{m}{\Omega}\right)r^2} \]  
(4)

\[ \Omega = E[r^2] \]  
(5)

\[ m = \frac{\Omega^2}{\text{var}(r^2)} \geq 0.5 \]  
(6)

for m=1 we have a Rayleigh fading channel, as m increase the channel becomes non-fading, at the other extreme, for m=1/2 we have a one sided Gaussian distribution. For Nakagami -m fading channel with appropriate sampling, the discrete representation is as follows:

\[ y_k = a_k x_k + n \]  
(7)

where, \(k\) is an integer symbol index, \(x_k\) is a BPSK symbol amplitude, \(n_k\) is the additive white Gaussian noise (AWGN) component with zero mean and power spectral density \(N_0/2\). The fading amplitude \(a_k\) follows a Nakagami PDF. The simulation of Nakagami-m fading amplitude can be introduced as follows:

\[ \text{Y}_k = \text{Y}_{1k} + \text{Y}_{2k} + \text{Y}_{3k} + \ldots + \text{Y}_{mk} \]  
(9)

Y, is gamma distributed so, taking the square root of \((Y)\), then \(Z=\sqrt{Y}\), where \((Z)\) represent the fading amplitude for Nakagami-m fading channel.

### IV. Decoding of Turbo Code Using MAP Algorithm

In 1974, an algorithm, which has become known as maximum aposteriori probability (MAP) algorithm by Bahl et al [10]. In order to estimate the a posteriori probabilities of the states and the transition of a Markov source observed in memory less channel noise. Bahl et al showed how the algorithm could be used to decode both block and convolutional codes. The basic idea is to break up decoding of a fairly complex and long code into steps while the transfer of probabilities or “soft” information between the decoding steps guarantees almost no losses of information [11]. MAP algorithm provides not only the estimated bit sequence, but also the probabilities for each bit that it has been decoded correctly. The decoder depicted in Fig.2.is made up of two elementary decoders (DEC1 and DEC2) in a serial concatenated scheme. For a discrete memoryless Gaussian channel and binary modulation, the decoder is made up of a couple \(R_k\) of two random variables \(x_k\) and \(y_k\) at time \(k\).

\[ x_k = (2X - 1) + i_k \]  
\[ y_k = (2X - 1) + q_k \]  
(10)

\[ \text{here } i_k \text{ and } q_k \text{ are two independent noises with the same variance.} \]

The LLR, \(A_1(d_k)\) associated with each decoded bit \(d_k\) from sequences \\{\(x_k\)\} and \\{\(y_k\)\} by the first decoder can be expressed as follows:

\[ A_1(d_k) = \log \frac{\Pr(d_k = 1/observation)}{\Pr(d_k = -1/observation)} \]  
(12)

where, \(\Pr(d_k = i/observation)\), \(i = (0, 1)\) is the a posteriori probability (APP) of the bit \(d_k\).

After LLR computation of \(A_1(d_k)\) by the first decoder, the second decoder DEC2 performs the decoding of sequence \{\(d_k\)\} from the sequences \{\(A_1(d_k)\)\} and \{\(y_k\)\} following the global decoding rule is not optimum, because the first decoder uses only the fraction of the available redundant information. Therefore, it is possible to improve the performance of this serial decoder by using a feedback loop \(A_1(d_k)\) can be expressed as follows:

\[ A_1(d_k) = \log \frac{\sum m \sum j \gamma (R_k, m', m) a_k(m') \beta_k(m)}{\sum m \sum j \gamma (R_k, m, m) a_k(m) \beta_k(m)} \]  
(13)

The global decoding principle in accordance with serial Concatenation

The received sequence \(y_k\)

\[ X_k \rightarrow \text{16 stages Decoder DEC1} \rightarrow \text{Interleaver} \rightarrow \text{16 stages Decoder DEC2} \rightarrow \text{A1(d_k)} \rightarrow \text{A1(d_n)} \rightarrow \hat{d}_n \]

Fig. 2 Decoding Principle in accordance with serial Concatenation
where \( m, m' \) are the present and previous state, \( \gamma \) is the probability that given the trellis was in state \( m' \) at time \( k-1 \), it moves to state \( m \), \( \alpha \) is the probability that the trellis is in state \( m' \) at time \( k-1 \) for a specific received channel sequence. Finally, \( \beta \) is the probability for the received channel sequence given that the trellis at state \( m \) at time \( k \).

With the feedback loop the first decoder now has the following three data inputs \((x_k, y_{1k}, z_k)\) where \( z_k \) equal \( w_{2k} \) is the extrinsic information from the second decoder. The term turbo-code is given for this feedback decoder scheme with reference to the principle of the turbo engine as shown in Fig.3.

![Fig.3 Feedback Decoder used in Decoding Turbo-Codes](image)

V. PERFORMANCE OF TURBO CODE IN NAKAGAMI MULTIPATH M- FADING CHANNEL

The standard parameters used in our simulation can be described as follows: The encoder components are two identical recursive convolutional codes. The recursive parameters are \( G_0 = 7 \) & \( G_1=5 \) & \( K=3 \) & \( m=2 \) & \( K =1 \). The component decoder is (MAP) decoder. The number of iteration used in the decoding process (8 iterations), The Nakagami shaping factor \( m \) equal(1:3) The interleaver is considered to be 1000 bit random interleaver. The modulation technique is binary phase shift keying (BPSK). Punctured used is half parity bits from each encoder give a half rate code. The input data frame lengths are \{169-1000-10,000\} bit. The effect of the code rate and frame length of input data on the BER performance of turbo-codes over an (AWGN) channel is shown in Fig (4,5) respectively. For wireless applications on fading channels, channel coding is an important tool for improving communications reliability.

Turbo- codes perform near optimum capacity limit on (AWGN) channel [1]. As a powerful coding technique, turbo-codes offer great promise for improving the reliability of communications over wireless channels where fading is problematic [2]. The BER performance of turbo- codes with code rates 1/2 and 1/3 over a Rayleigh fading channel is shown in Fig (6,7) respectively. It should be noted that for the Rayleigh channel with average energy of unity, \( EA[a] \) is equal 0.8862.

![Fig.4 BER Performance Comparison Between One - Third and Half – Rate Turbo-Code](image)

![Fig.5 Effect of Frame – Length on the BER Performance of Turbo-Code](image)

![Fig.6 BER Performance of Turbo - Code with Different Frame Lengths (L) and Rate 1/2 over Rayleigh Fading Channel](image)
The BER performance of turbo-codes in Nakagami multipath m-fading channel with code rate 1/2 for different values of shaping factor m, and different frame lengths is shown in Fig.8 (a,b,c) and for code rate 1/3 in Fig.9 (a,b,c) respectively. For m equal(1) the BER performance obtained is the same as the BER performance over a Rayleigh fading channel.

For m=2 additional improvement is occurred, for m equal (3) the BER performance approached the performance over the AWGN channel especially for long frame length of input data where the difference is approximately (0.1) dB as shown in Table. I.

The turbo code BER performance with rate 1/2 in both Gaussian channel and Nakagami multipath fading channel has been also compared.

<table>
<thead>
<tr>
<th>Data frame length</th>
<th>(169) bit</th>
<th>(1000) bit</th>
<th>(10000) bit</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>BER</td>
<td>E_b/N_0 (dB)</td>
<td>BER</td>
</tr>
<tr>
<td>AWGN</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>10^{-4}</td>
<td>2.7</td>
<td>10^{-4}</td>
</tr>
<tr>
<td>Nakagami fading channel with m=3</td>
<td>10^{-4}</td>
<td>3.6</td>
<td>10^{-4}</td>
</tr>
<tr>
<td>(E_b/N_0) differences in (dB)</td>
<td>0.9</td>
<td>0.5</td>
<td>0.1</td>
</tr>
</tbody>
</table>
The BER performance comparison of turbo codes is listed in tables (II, III).

### Table II
**BER Performance of Rate 1/3 Turbo Codes in Both Rayleigh and Nakagami Fading Channels**

<table>
<thead>
<tr>
<th>Data frame length</th>
<th>169 bit</th>
<th>1000 bit</th>
<th>10000 bit</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Rayleigh fading channel</strong></td>
<td>BER</td>
<td>Eb/N0 (dB)</td>
<td>BER</td>
</tr>
<tr>
<td>10^4</td>
<td>4.13</td>
<td>10^4</td>
<td>2.3</td>
</tr>
<tr>
<td><strong>Nakagami fading channel with m=3</strong></td>
<td>10^4</td>
<td>2.9</td>
<td>10^4</td>
</tr>
<tr>
<td>(Eb/N0) differences in (dB)</td>
<td>1.23</td>
<td>0.6</td>
<td>0.3</td>
</tr>
</tbody>
</table>

### Table III
**BER Performance of Rate 1/2 Turbo Codes in Both Rayleigh and Nakagami Fading Channels**

<table>
<thead>
<tr>
<th>Data frame length</th>
<th>169 bit</th>
<th>1000 bit</th>
<th>10000 bit</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Rayleigh fading channels</strong></td>
<td>BER</td>
<td>Eb/N0 (dB)</td>
<td>BER</td>
</tr>
<tr>
<td>10^4</td>
<td>5.14</td>
<td>10^4</td>
<td>3.85</td>
</tr>
<tr>
<td><strong>Nakagami fading channel with m=3</strong></td>
<td>10^4</td>
<td>3.6</td>
<td>10^4</td>
</tr>
<tr>
<td>(Eb/N0) differences in (dB)</td>
<td>1.54</td>
<td>1.55</td>
<td>1.7</td>
</tr>
</tbody>
</table>

### VI. Conclusion

The simulation results for the BER performance of turbo codes in different channel models show that: in Nakagami multipath fading channel with code rate 1/2 and shaping factor m equal (3), the BER performance is similar to that obtained over a Rayleigh multipath fading channel with code rate 1/3, it means, the efficient using of channel bandwidth can be obtained without degradation of the BER performance. On the other side, while the BER performance improved as the shaping parameter (m) increased, for (m) greater than (3) no additional improvements have been achieved.

### References


